# NIMROD CURTIS

M.Sc Robotics | Robotics & AI Researcher

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# ABOUT

Passionate M.Sc. in Robotics student driven by a fervor for technology and science, with a strong focus on algorithms and deep learning for autonomous systems. A dedicated team player with exceptional communication skills, a quick learner, and committed to continuous improvement.

#### RESEARCH EXPERIENCE & ACADEMY

#### 2022-Present

# M.Sc in Robotics, Mechanical Engineering, Tel Aviv University

• GPA 95/100

Research Area:

- Learning tracking skills from human demonstrations across robots.
- Human-Robot Interaction and perception for smart exoskeleton (ICRA2024 workshop).

From initial research and solution design to final implementation and development of deep learning algorithms.

### Research Assistant at Tel-Aviv University's Robotics Lab | web

Learning in-hand perception and manipulation with robotic hands and sim2real

- 1.\*Azulay, O., \*Curtis, N., Sintov, A., \*Mizrahi, A., (2023). Augmenting Tactile Simulators with Real-like and Zero-Shot Capabilities. ICRA 2024 | arXiv.
- 2. Azulay, O., <u>Curtis, N.</u>, Sintov, A et al. (2023). AllSight: A Low-Cost and High-Resolution Round Tactile Sensor with Zero-Shot Learning Capability. IEEE RAL | <u>arXiv</u>.

  \*Equal contribution

#### 2018-2022

## B.Sc, Mechanical Engineering, Tel Aviv University

Developed an autonomous mobile robotic cart |

SW: python,C/C++,ROS | HW: Nvidia Jetson nano, Arduino Mega.

Demonstrating robotics knowledge, software engineering, and hardware integration to solve a real-world problem. (Outstanding project acheivment).

**Relevant Coursework**: Deep learning | , SLAM and perception for autonomous navigation | Computer Vision, Human-Robot Interaction, Introduction to Robotics (+Lab), Control theory, Systems Dynamics and Control, Computational Intelligence

## PROFESSIONAL EXPERIENCE

#### 2022-Present

#### Course Instructor - Computational Intelligence

Designed and delivered hands-on python exercises covering topics such as genetic algorithms for optimization, fuzzy logic and intro to ML & DL  $| \bigcirc \rangle$ 

# 2020-2022

# Integration Engineer, Indoor Robotics

Build, operate and design tests of autonomous drones and docking systems. Applied electronics expertise, optimized processes, and leveraged lab experience.

#### IDF MILITARY SERVICE

# Combat Service in the Submarine Unit | Sergeant major

2012-2016

- Commander at the unit training course
- Contributed in a combat position within the Submarine's Weapons Department.
- Outstanding cadet in the submarines training course (Class 103)

#### **SOFTWARE** AWARDS **INTEREST** • Robotics Awarded the Faculty Scholarships for M.Sc Programming Python, C++, MATLAB · Deep learning excellence (2024) PyTorch, OpenCV • Computer vision Tools & libraries Git, Linux, ROS(1/2) • Human-Robot Interaction LANGUAGE · Perception Hebrew - Native Engineering Solidworks, 3D English - Excellent printing, Mechatronics